

Exploitable Results by Third Parties

15015 ENTOC

Project details

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Name: Boiler-plate Requirements Specification Tool		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> Plant description 	<ul style="list-style-type: none"> Formalized description of requirements by means of boilerplates 	<ul style="list-style-type: none"> Plant description enriched with requirements
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Formalization of Requirements Compatibility with the AutomationML format Flexibility in the formalization 	
Integration constraint(s):	<ul style="list-style-type: none"> Java Runtime Environment 	
Intended user(s):	<ul style="list-style-type: none"> Requirement Engineers, Plant Design Engineers 	
Provider:	<ul style="list-style-type: none"> TWT GmbH Science & Innovation 	
Contact point:	<ul style="list-style-type: none"> Christian König – christian.koenig@tw-t-gmbh.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Commercial license 	
<i>Latest update: 07/01/2019</i>		

Name: Product and Process Requirement Analyz3r		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> Plant and product description 	<ul style="list-style-type: none"> Schedule Optimization Resource Dead-Locks avoidance 	<ul style="list-style-type: none"> Optimized production schedule
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Formalized variability handling Automatic resource Dead-Locks avoidance Compatibility with AML as information source 	
Integration constraint(s):	<ul style="list-style-type: none"> Java Runtime Environment 	
Intended user(s):	<ul style="list-style-type: none"> Requirement Engineers, Plant Design Engineers 	
Provider:	<ul style="list-style-type: none"> Chalmers University of Technology 	
Contact point:	<ul style="list-style-type: none"> Knut Åkesson knut.akesson@chalmers.se 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Licence to be negotiated 	
<i>Latest update: 07/01/2019</i>		

Name: Requirements-Add-on for 3D Modelling Tool		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> Requirement lists in AML-format 	<ul style="list-style-type: none"> Import of AML-files including RoleClasses Assigning requirements to 3D objects or hierarchy-nodes 	<ul style="list-style-type: none"> 3D Plant data model including formalized requirements
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Combination of 3D layout design and requirements specification in one tool 	
Integration constraint(s):	<ul style="list-style-type: none"> Operating System: Microsoft Windows Installation of software taraVRbuilder 	
Intended user(s):	<ul style="list-style-type: none"> Planners for plants and material-handling systems 	
Provider:	<ul style="list-style-type: none"> tarakos GmbH 	
Contact point:	<ul style="list-style-type: none"> klaus.hanisch@tarakos.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> commercial licence to be negotiated 	
<i>Latest update: 07/01/2019</i>		

Name: Rule-based AML-interface-		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ AML-file ▪ varying rulesets for interpretation 	<ul style="list-style-type: none"> ▪ Import of AML-files including varying dialects, RoleClasses or SystemUnitClass Libs 	<ul style="list-style-type: none"> ▪ Flexible AutomationML-interface considering several individual or standardized role-class and SystemUnitClass specifications
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ AML interface is able to read and write many kinds of AML- libraries ▪ Enterprise- or domain specific AML-structures are read-/writeable as well as standardized libraries 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Operating System: Microsoft Windows ▪ Installation of software taraVRbuilder required ▪ Stand alone tool on request 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Planners for plants and material-handling systems ▪ IT specialists who need to convert data among different engineering tools or AML-dialects 	
Provider:	<ul style="list-style-type: none"> ▪ tarakos GmbH 	
Contact point:	<ul style="list-style-type: none"> ▪ klaus.hanisch@tarakos.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ commercial licence to be negotiated 	

Latest update: 07/01/2019

Name: Process Planning Tool-		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> AML-file including plant resource structure 	<ul style="list-style-type: none"> User defines process steps and selects one or more needed resources for every step supported by the imported resource list 	<ul style="list-style-type: none"> AML-file containing resources, processes and dependencies among them
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Tool enables to create an integrated plant data model including resources, processes and their dependencies Resource structure can be imported from different tools 	
Integration constraint(s):	<ul style="list-style-type: none"> Operating System: Microsoft Windows 	
Intended user(s):	<ul style="list-style-type: none"> Planners for plants and material-handling systems 	
Provider:	<ul style="list-style-type: none"> tarakos GmbH 	
Contact point:	<ul style="list-style-type: none"> klaus.hanisch@tarakos.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> commercial licence to be negotiated 	
<i>Latest update: 07/01/2019</i>		

Name: Web based planning tool – proof of concept		
Input(s):	Main feature(s)	Output(s):
	<ul style="list-style-type: none"> Users can design 3D layouts at a browser based application by using 3D object libraries for material handling and manufacturing systems 	<ul style="list-style-type: none"> web based planning tool for material handling and manufacturing
Unique Selling Proposition(s):	<ul style="list-style-type: none"> low barrier for IT administration compared to desktop installation easy access for users cross-platform application, also available at mobile devices 	
Integration constraint(s):	<ul style="list-style-type: none"> Mozilla Firefox, Chrome 	
Intended user(s):	<ul style="list-style-type: none"> Planners for plants and material-handling systems 	
Provider:	<ul style="list-style-type: none"> tarakos GmbH 	
Contact point:	<ul style="list-style-type: none"> klaus.hanisch@tarakos.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Proof of concept - commercial licence to be negotiated 	
<i>Latest update: 07/01/2019</i>		

Name: Tool for project milestone planning		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> AutomationML files with a resource hierarchy 	<ul style="list-style-type: none"> Formalized description of project planning information for creation of production equipment 	<ul style="list-style-type: none"> Original AML file enriched by milestone information
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Formalized project information to be exchanged between customers and suppliers of production equipment Easy import of project planning information into ERP systems of equipment suppliers Clearness of what to deliver and when to deliver Usable for project tracking 	
Integration constraint(s):	<ul style="list-style-type: none"> Python 2.7 interpreter 	
Intended user(s):	<ul style="list-style-type: none"> Planners for production systems 	
Provider:	<ul style="list-style-type: none"> Institut für Automation und Kommunikation e.V. (ifak) 	
Contact point:	<ul style="list-style-type: none"> Mario Thron - mario.thron@ifak.eu 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Research and development contract to ifak 	
<i>Latest update: 07/01/2019</i>		

Name: Standardized requirement specification language - milestone definition		
Input(s):	Main feature(s)	Output(s):
	<ul style="list-style-type: none"> Formalized description of project planning information for creation of production equipment 	<ul style="list-style-type: none"> Intended: Best Practice Recommendation at AutomationML e.V.
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Formalized project information to be exchanged between customers and suppliers of production equipment 	
Integration constraint(s):	<ul style="list-style-type: none"> Software tools for handling XML (specifically AutomationML based on CAEX 2.15 schema) 	
Intended user(s):	<ul style="list-style-type: none"> Industrial planners of production equipment 	
Provider:	<ul style="list-style-type: none"> Intended publisher: AutomationML e.V. 	
Contact point:	<ul style="list-style-type: none"> Later on for: office@automationml.org During preparation time: Mario Thron – mario.thron@ifak.eu 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Public available 	
<i>Latest update: 07/01/2019</i>		

Name: Standardized requirement specification language - material handling		
Input(s):	Main feature(s)	Output(s):
	<ul style="list-style-type: none"> Standardized specification of material handling systems by using AutomationML 	<ul style="list-style-type: none"> standardization
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Unification for data exchange among engineering tools related to material handling domain 	
Integration constraint(s):		
Intended user(s):	<ul style="list-style-type: none"> Planners and automation technicians of material handling domain 	
Provider:	<ul style="list-style-type: none"> AutomationML e.V. 	
Contact point:	<ul style="list-style-type: none"> klaus.hanisch@tarakos.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Public document 	
<i>Latest update: 07/01/2019</i>		

Name: Component description (White paper) - Chapter Simulation (FMU)		
Input(s):	Main feature(s)	Output(s):
	<ul style="list-style-type: none"> ▪ Standardized description of interconnections between simulation models of different vendors. ▪ Based on AutomationML and Functional Mockup Interface technologies. 	<ul style="list-style-type: none"> ▪ Public available whitepaper
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Specification of a set of different simulation models, which appear in a co-simulation environment. 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ FMI co-simulators, which must be prepared to interpret the data according to this whitepaper ▪ FMI co-simulation models 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Planners of production equipment ▪ Users of virtual commissioning scenarios 	
Provider:	<ul style="list-style-type: none"> ▪ Intended publisher: AutomationML e.V. 	
Contact point:	<ul style="list-style-type: none"> ▪ Later on for: office@automationml.org ▪ During preparation time: Mario Thron – mario.thron@ifak.eu 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Public available 	
<i>Latest update: 07/01/2019</i>		

Name: AML-FMU Configurator		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ AutomationML file of a production system ▪ Functional mock-up Interfaces (FMUs) 	<ul style="list-style-type: none"> ▪ Link Functional Mock-up Interfaces to AML ▪ Set initialize values of FMUs inputs ▪ Link in- & outputs between FMUs 	<ul style="list-style-type: none"> ▪ Extended AML file with FMUs & how setup for a co-simulator via FMUs
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Standalone prototype tool which use just standard data formats ▪ Create an extended AML file without tool dependencies 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Prototype ▪ No all functions are tested jet ▪ No all functions are realized ▪ Use of non-official public extensions of the AML standard to link FMUs 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Create & setup the virtual behavior plant model for virtual commissioning 	
Provider:	<ul style="list-style-type: none"> ▪ EKS InTec GmbH 	
Contact point:	<ul style="list-style-type: none"> ▪ anton.strahilov@eks-intec.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ AML must fix the suggestion to extend the AML standard by linking of FMUs 	

Latest update: 07/01/2019

Name: Engineering Model Store Prototype		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Packages of engineering data (from equipment manufacturers) 	<ul style="list-style-type: none"> ▪ Handling of packages, which include AutomationML files and behavior models in form of FMI models. ▪ Automatic dependency management 	<ul style="list-style-type: none"> ▪ sets of packages of engineering data to be used in co-simulation scenarios
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Package management including dependencies between packages and versions of packages, even if they are originally provided by different equipment manufacturers 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ The server provides an HTTP based REST service API 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Companies, which provide virtual commissioning scenarios. 	
Provider:	<ul style="list-style-type: none"> ▪ Institut für Automation und Kommunikation e.V. (ifak) 	
Contact point:	<ul style="list-style-type: none"> ▪ Mario Thron - mario.thron@ifak.eu 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Research and development contract to ifak 	
<i>Latest update: 07/01/2019</i>		

Name: AddOn for Planning Tool - Access to different model stores-		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> 3D data from online CAD-catalogues 	<ul style="list-style-type: none"> Send request to model stores Selection, download, conversion and import of CAD-models 	<ul style="list-style-type: none"> Access to CAD-models of manufacturers for layout planning aspects
Unique Selling Proposition(s):	<ul style="list-style-type: none"> User-Access to amounts of precise CAD models of manufacturers for detailed layout planning 	
Integration constraint(s):	<ul style="list-style-type: none"> Operating System: Microsoft Windows Installation of software taraVRbuilder required 	
Intended user(s):	<ul style="list-style-type: none"> Planners for plants and material-handling systems 	
Provider:	<ul style="list-style-type: none"> tarakos GmbH 	
Contact point:	<ul style="list-style-type: none"> klaus.hanisch@tarakos.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> commercial licence to be negotiated 	
<i>Latest update: 07/01/2019</i>		

Name: Collada import to AGX Dynamics		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> A scene description with physics according to the COLLADA 1.4 standard 	<ul style="list-style-type: none"> Parsing, interpretation, and translation of COLLADA concepts into AGX Dynamics entities. 	<ul style="list-style-type: none"> Representation of the described simulation contents within the AGX Dynamics simulation engine
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Industry grade real time physics for COLLADA models 	
Integration constraint(s):	<ul style="list-style-type: none"> Requires AGX Dynamics, which is available for Windows, Linux and macOS 	
Intended user(s):	<ul style="list-style-type: none"> Users of modeling and authoring tools that generate COLLADA documents and require high quality industry grade simulations 	
Provider:	<ul style="list-style-type: none"> Algoryx Simulation 	
Contact point:	<ul style="list-style-type: none"> contact@algoryx.se 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Commercial license 	
<i>Latest update: 07/01/2019</i>		

Name: FMU export from AGX Dynamics		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> Simulation model in the AGX Dynamics physics engine 	<ul style="list-style-type: none"> Creation of an FMU from an AGX Dynamics scene specification. 	<ul style="list-style-type: none"> An FMU containing the simulation scene along with bootstrapping functionality to integrate with an existing AGX Dynamics installation
Unique Selling Proposition(s):	<ul style="list-style-type: none"> By exporting an AGX Dynamics scene as an FMU one gets access to high quality industry grade simulations of jointed multibody systems with frictional contacts within the FMI ecosystem, enabling integration with simulation models from a multitude of other sources. 	
Integration constraint(s):	<ul style="list-style-type: none"> Requires AGX Dynamics, which is available for Windows, Linux and macOS 	
Intended user(s):	<ul style="list-style-type: none"> Organizations already using a specialized simulation software for some part of their design, but who also need the precision and stability of AGX Dynamics for the parts of the scene that is not handled by the specialized simulation software 	
Provider:	<ul style="list-style-type: none"> Algoryx Simulation 	
Contact point:	<ul style="list-style-type: none"> contact@algoryx.se 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Commercial license. 	

Latest update: 07/01/2019

Name: FMU export from Momentum		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> Mechanical design in the Algoryx Momentum plugin for the ANSYS SpaceClaim CAD software. 	<ul style="list-style-type: none"> Creation of an FMU from an Algoryx Momentum design. 	<ul style="list-style-type: none"> An FMU containing the simulation scene along with bootstrapping functionality to integrate with an existing AGX Dynamics installation.
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Efficient and unique combination of CAD and physics modeling for developing simulation components that can be readily exported as FMUs and integrated into FMI systems. 	
Integration constraint(s):	<ul style="list-style-type: none"> Requires Algoryx Momentum, a plugin for the ANSYS SpaceClaim CAD software, available for Windows. Running the FMU requires AGX Dynamics, which is available for Windows, Linux, and macOS. 	
Intended user(s):	<ul style="list-style-type: none"> Designers of mechanical sub-systems that need to provide digital models into the engineering tool chain for smart factories 	
Provider:	<ul style="list-style-type: none"> Algoryx Simulation 	
Contact point:	<ul style="list-style-type: none"> contact@algoryx.se 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Commercial license. 	

Latest update: 07/01/2019

Name: Co-Simulation master		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ FMI-compliant component models ▪ Plant configuration 	<ul style="list-style-type: none"> ▪ Co-Simulation of models for Virtual Engineering of systems 	<ul style="list-style-type: none"> ▪ Signal traces
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Easy integration in Siemens NX MCD (through the EDAG PLC Connect) possible, but not necessary 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Python 3 interpreter 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Engineers for Virtual Engineering of plants 	
Provider:	<ul style="list-style-type: none"> ▪ TWT GmbH Science & Innovation 	
Contact point:	<ul style="list-style-type: none"> ▪ Christian König – christian.koenig@tw-t-gmbh.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Commercial licenses 	
<i>Latest update: 07/01/2019</i>		

Name: PLC Connect FMU interface		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> FMI-compliant component models 	<ul style="list-style-type: none"> Simulation of FMUs during concept design in CAD system NX Simulation of FMUs for virtual commissioning in CAD system, NX 	<ul style="list-style-type: none"> Fully simulated 3D design
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Easy integration in Siemens NX MCD One FMU integration for virtual engineering and virtual commissioning 	
Integration constraint(s):	<ul style="list-style-type: none"> Based on TWT Co-Simulation master EDAG PLC Connect necessary 	
Intended user(s):	<ul style="list-style-type: none"> Engineers doing virtual engineering and virtual commissioning, NX users 	
Provider:	<ul style="list-style-type: none"> EDAG PS 	
Contact point:	<ul style="list-style-type: none"> ali.moghaddam.nejad@edag-ps.com 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Commercial licenses for NX and PLCConnect which can be acquired from EDAG PS 	
<i>Latest update: 07/01/2019</i>		

Name: RF:CSPy FMI Co-Simulator		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Extended AML file (WP3 AML-FMU Configurator) ▪ FMUs (local or from FMU store) 	<ul style="list-style-type: none"> ▪ Ran a simulation of several FMUs in a simulation step between 1 and 25 [ms] ▪ Communicate with all tools of RF::Suite 	<ul style="list-style-type: none"> ▪ Preformat simulation of FMUs for virtual commissioning
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Using only standard data formats ▪ Useful with RF::Suite tools ▪ Support FMI 1.0 & 2.0 version at same time 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Is a prototype no a final tool ▪ Not all tests performed ▪ No all function realized ▪ Several bugs open 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Engineer for virtual commissioning 	
Provider:	<ul style="list-style-type: none"> ▪ EKS InTec GmbH 	
Contact point:	<ul style="list-style-type: none"> ▪ anton.strahilov@eks-intec.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ commercial 	
<i>Latest update: 07/01/2019</i>		

Name: Augmented Reality Model Creator (ARMCor)		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> Native 3d cad data 	<ul style="list-style-type: none"> Support preparing of AR needed project Create automated AR project for DIOTA player 	<ul style="list-style-type: none"> DIOTA player project
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Reduce preparation time (more than 95%) Reduce update time of existing DIOTA player projects (deepens on complexity) 	
Integration constraint(s):	<ul style="list-style-type: none"> DIOTA API doesn't support color definition ARMCor is a prototype 	
Intended user(s):	<ul style="list-style-type: none"> Each mechanical engineer & maintenance owner 	
Provider:	<ul style="list-style-type: none"> EKS InTec GmbH 	
Contact point:	<ul style="list-style-type: none"> anton.strahilov@eks-intec.de 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Design & develop ARMCor as a tool Extension of DIOTA player API by function to manipulate color informations of the 3d geometry objects 	
<i>Latest update: 07/01/2019</i>		

Name: Cable damage estimation model		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> AGX Dynamics simulation containing one or more cables 	<ul style="list-style-type: none"> Estimation of damage and wear to a cable due to deformation and impacts/contact with itself, other cables or the surrounding environment. 	<ul style="list-style-type: none"> Account of when, where, and why damage and wear was caused to a simulated cable.
Unique Selling Proposition(s):	<ul style="list-style-type: none"> The wear estimation is based on both deformations and contact forces. The deformation part has its basis in the physics on wire strain 	
Integration constraint(s):	<ul style="list-style-type: none"> Requires AGX Dynamics, which is available for Windows, Linux and macOS. 	
Intended user(s):	<ul style="list-style-type: none"> Robot operators and programmers who wish to optimize their robot programming and dresspack mounting to minimize cable wear and production down time. Manufacturing designers where the assembled part contain wires or cables. 	
Provider:	<ul style="list-style-type: none"> Algoryx Simulation 	
Contact point:	<ul style="list-style-type: none"> contact@algoryx.se 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Commercial license. 	
<i>Latest update: 07/01/2019</i>		

Name: Automatic cable parameters identification		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> Real-world cable for which simulation parameters are to be identified 	<ul style="list-style-type: none"> A process and software for identifying simulation parameters based on behavior and response of a real-world cable. 	<ul style="list-style-type: none"> List of AGX Dynamics cable material parameter values
Unique Selling Proposition(s):	<ul style="list-style-type: none"> Accurate material parameter values ensure that the behavior and response of the simulated cable as close as possible matches the would-be behavior and response of a read-world cable in the same situation. 	
Integration constraint(s):	<ul style="list-style-type: none"> Requires AGX Dynamics, which is available for Windows, Linux and macOS. 	
Intended user(s):	<ul style="list-style-type: none"> Designers of manufacturing processes involving cables where accurate positioning and dynamics of the cable is important. 	
Provider:	<ul style="list-style-type: none"> Algoryx Simulation 	
Contact point:	<ul style="list-style-type: none"> contact@algoryx.se 	
Condition(s) for reuse:	<ul style="list-style-type: none"> Commercial license. 	
<i>Latest update: 07/01/2019</i>		

Name: Process for updating the digital twin		
Input(s):	Main feature(s)	Output(s):
<ul style="list-style-type: none"> ▪ Photos of production system ▪ Digital twin 	<ul style="list-style-type: none"> ▪ Flexible scanning ▪ Automatic comparison and identification ▪ Pose and position estimation 	<ul style="list-style-type: none"> ▪ Updated digital twin
Unique Selling Proposition(s):	<ul style="list-style-type: none"> ▪ Automatic update of digital twin based on geometrical changes ▪ Automatic classification and identification ▪ Flexible scanning using photogrammetry 	
Integration constraint(s):	<ul style="list-style-type: none"> ▪ Python 	
Intended user(s):	<ul style="list-style-type: none"> ▪ Production preparation and maintenance engineers 	
Provider:	<ul style="list-style-type: none"> ▪ Chalmers University of Technology 	
Contact point:	<ul style="list-style-type: none"> ▪ Petter Falkman petter.falkman@chalmers.se 	
Condition(s) for reuse:	<ul style="list-style-type: none"> ▪ Licence to be negotiated 	
<i>Latest update: 07/01/2019</i>		